Mid-term Exam

11 Feb., 2016

<u>Professor</u>: J.D. Wilson <u>Time available</u>: 75 mins <u>Value</u>: 15%

Please answer four questions: 4 x 4% \rightarrow 16%

1. The principle of "conservation of mass" can be expressed quite generally by the equation

$$\frac{\partial \phi}{\partial t} = -\nabla \cdot \mathbf{F} + Q , \qquad (1)$$

where $\phi \, [\text{kg m}^{-3}]$ is the volumetric concentration of the species of interest. Identify the assumptions or restrictions or simplifications whose introduction leads from Eq. (1) to the "diffusion equation"

$$\frac{\partial \phi}{\partial t} = \mathcal{D}_{\phi} \frac{\partial^2 \phi}{\partial x^2} , \qquad (2)$$

where \mathcal{D}_{ϕ} is the molecular diffusivity of the species ϕ .

This is similar to short answer question 2 of the 2007 exam. Answer:

- assume there are no sources or sinks, i.e. Q = 0
- assume there is only one space dimension^{**}, x, such that

$$\frac{\partial \phi}{\partial t} = -\frac{\partial F_x}{\partial x}$$

**or (equivalently), assume that symmetry prevails along other spatial axes such that $\partial F_y/\partial y = \partial F_z/\partial z = 0$.

• assume the flux of ϕ along x is purely diffusive, i.e. $F_x = -\mathcal{D}_{\phi} \partial \phi / \partial x$, such that

$$\frac{\partial \phi}{\partial t} = -\frac{\partial}{\partial x} \left(-\mathcal{D}_{\phi} \frac{\partial \phi}{\partial x} \right)$$

• assume the diffusivity is independent of position, then

$$\frac{\partial \phi}{\partial t} = \mathcal{D}_{\phi} \frac{\partial^2 \phi}{\partial x^2}$$

2. Perform a dimensional analysis to find a law for the terminal velocity w of a spherical particle of radius r and density ρ in still air with density ρ_a and kinematic viscosity ν [m² s⁻¹]. The particle is subject to a gravitational force (per unit mass) given by g [m s⁻²].

Answer: The number n of variables involved is n = 6, while the number of fundamental dimensions is m = 3. Therefore one seeks a relationship between n - m = 3 independent dimensionless variables, i.e. an expression of form

$$\pi_1 = f(\pi_2, \pi_3)$$

where π_1 will be the ratio of the terminal velocity w to some suitable scale for velocity such as, say, \sqrt{rg} . As to the arguments (π_2, π_3) of the unknown function, one of them can be chosen as ρ/ρ_a (or its reciprocal; either is equally acceptable). So we have

$$\frac{w}{\sqrt{rg}} = F\left(\frac{\rho}{\rho_a}, \theta\right)$$

where θ is the third, and as yet unspecified, dimensionless variable. How to specify the latter? We haven't yet "used" the kinematic viscosity ν , so any ratio we form using ν will be independent of the two we've already chosen. How to make ν dimensionless? Notice that the units of $\sqrt{r^3g}$ are m² s⁻¹, the same as those of ν . Thus, finally,

$$\frac{w}{\sqrt{rg}} = F\left(\frac{\rho}{\rho_a}, \frac{\nu}{\sqrt{r^3g}}\right) \;.$$

(Note: this is a simplified version of short answer question 2 of the 2009 exam, repeated as short answer question 1 of the 2010 exam. Notice that you did not need to do a laborious manipulation using the method of indices; however if you did choose to do so, carried through correctly it would have given the correct result.)

3. Determine the 4×4 tridiagonal coefficient matrix \mathbf{M} and the right hand side \mathbf{B} in a matrix expression of form $\mathbf{M} \ \mathbf{\Theta} = \mathbf{B}$ for the numerical solution of

$$\frac{\partial^2 \theta}{\partial z^2} = 2$$

on $0 \leq z \leq 1$, subject to $\theta(0) = \theta(1) = 0$. Set up your solution with four, equi-spaced gridpoints indexed J = (1, 2, 3, 4) positioned at $z_J = (0, 1/3, 2/3, 1)$. Adopt the simple $O[\Delta z^2]$ computational molecule for the curvature at internal gridpoints (J = 2, 3). You need not invert **M**, nor obtain the (numerical) solution vector $\mathbf{\Theta} = (\theta_1, \theta_2, \theta_3, \theta_4)$.

Answer: You have the following four equations:

$$1 \times \theta_1 + 0 \times \theta_2 + 0 \times \theta_3 + 0 \times \theta_4 = 0$$

$$9 \times \theta_1 - 18 \times \theta_2 + 9 \times \theta_3 + 0 \times \theta_4 = 2$$

$$0 \times \theta_1 + 9 \times \theta_2 - 18 \times \theta_3 + 9 \times \theta_4 = 2$$

$$0 \times \theta_1 + 0 \times \theta_2 + 0 \times \theta_3 + 1 \times \theta_4 = 0$$

Thus,

$$\mathbf{M} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 9 & -18 & 9 & 0 \\ 0 & 9 & -18 & 9 \\ 0 & 0 & 0 & 1 \end{pmatrix} , \ \mathbf{B} = \begin{pmatrix} 0 \\ 2 \\ 2 \\ 0 \end{pmatrix}$$

(Note: this is a simplified version of short answer question 2 of the 2009 and 2010 exams).

4. Suppose a velocity "field" U = U(x, t) is self-advecting along the x axis, i.e. $\partial U/\partial t = -U \partial U/\partial x$, and that initially the field is a pure sine wave with wavelength λ , i.e. the initial condition is $U(x, 0) = \sin kx$ where $k = 2\pi/\lambda$ is the wavenumber. In this context, and given the identities

$$\sin(A+B) = \sin(A)\cos(B) + \cos(A)\sin(B),$$

$$\sin(A-B) = \sin(A)\cos(B) - \cos(A)\sin(B),$$

explain what is meant by "wave-wave interaction".

Answer: At t = 0, we have $\partial U/\partial x = k \cos kx$ and so $\partial U/\partial t = -k \sin(kx) \cos(kx)$. It follows that an infinitesimal time dt later,

$$U(x, dt) = \sin(kx) - k dt \sin(kx) \cos(kx) = \sin(kx) - \frac{k dt}{2} \sin(2kx)$$

because $\sin(A) \cos(A) \equiv \frac{1}{2} \sin(2A)$. Wave-wave interaction (wavenumber k_1 with wavenumber k_2 , though in this case $k_1 = k_2 = k$) produces waves of wavenumber $(k_1 + k_2)$ and $(k_1 - k_2)$.

5. Figure (1) shows a grid for the numerical solution of

$$\frac{\partial\theta}{\partial t} + U \,\frac{\partial\theta}{\partial x} = 0 \,, \tag{3}$$

discretized as (say)

$$\frac{\phi_I^{n+1} - \phi_I^n}{\Delta t} + U \frac{\phi_I^n - \phi_{I-1}^n}{\Delta x} \tag{4}$$

and with finite gridlengths $\Delta x = \text{const.}$, $\Delta t = \text{const.}$ The sloping lines¹ correspond to two different values of the advecting velocity U, assumed constant. Explain for which of the two velocities this setup would satisfy the CFL condition $U\Delta t/\Delta x \leq 1$, and why failure to do so would imply that the algorithm is unlikely to result in a satisfactory solution.

Answer: With the given algorithm, a "half-cone of influence" on the solution at (I, n) spreads outward along the x-axis towards smaller x by exactly the amount Δx for each increment Δt backward in time. We also know that the true value of $\theta(I, n) \equiv \theta(I\Delta x, n\Delta t)$ is $\theta(I\Delta x - Un\Delta t, 0)$, i.e. we look backward in time down the "ray" representing the physical velocity U and locate where it lies on the x axis at time t = 0. In the case that $U = U_1$, this ray *lies outside the half-cone of influence* so that $\theta^{\text{Num}}(I\Delta x, n\Delta t)$ cannot be influenced by the initial value at the proper point: the numerical solution must fail. Furthermore it is evident that $U_1\Delta t > \Delta x$, violating the CFL condition.

¹In the actual exam, line U_2 was wrongly drawn as a negative velocity, such that as time increased position x decreased.



Figure 1: A uniform grid. Vertical axis is time, indexed n; horizontal axis is distance x, indexed I.